Control System Design Goodwin Solution Manual

Actuator saturation is probably the most frequent nonlinearity encountered in control applications. Input saturation leads to controller windup, removable by structural modification during compensator realization and plant windup which calls for additional dynamics. This book presents solutions to the windup prevention problem for stable and unstable single-input-single-output and multiple-input-multiple-output (MIMO) systems.
This book is dedicated to Prof. Peter Young on his 70th birthday. Professor Young has been a pioneer in systems and control, and over the past 45 years he has influenced many developments in this field. This volume comprises a collection of contributions by leading experts in system identification, time-series analysis, environmetric modelling and control system design – modern research in topics that reflect important areas of interest in Professor Young's research career. Recent theoretical developments in and relevant applications of these areas are explored treating the various subjects broadly and in depth. The authoritative and up-to-date research presented here will be of interest to academic researcher in control and disciplines related to environmental research, particularly those to with water systems. The tutorial style in which many of the contributions are composed also makes the book suitable as a source of study material for graduate students in those areas.
This is the biggest, most comprehensive, and most prestigious compilation of articles on control systems imaginable. Every aspect of control is expertly covered, from the mathematical foundations to applications in robot and manipulator control. Never before has such a massive amount of authoritative, detailed, accurate, and well-organized information been available in a single volume. Absolutely everyone working in any aspect of systems and controls must have this book!
The material presented in this volume represents current ideas, knowledge, experience and research results in various fields of control system design.
Analysis and Design
Modeling, Diagnostics and Process Control
An Introduction to State-Space Methods
Automatic Control Systems
PID Control System Design and Automatic Tuning using MATLAB/Simulink
Mechatronics: Ideas for Industrial Applications
Structures and Algorithms

This book contains a derivation of the subset of stabilizing controllers for analog and digital linear time-invariant multivariable feedback control systems that insure stable system errors and stable controller outputs for persistent deterministic reference inputs that are trackable and for persistent deterministic disturbance inputs that are rejectable. For this subset of stabilizing controllers, the Wiener-Hopf methodology is then employed to obtain the optimal controller for which a quadratic performance measure is minimized. This is done for the completely general standard configuration and methods that enable the trading off of optimality for an improved stability margin and/or reduced sensitivity to plant model uncertainty are described. New and novel results on the optimal design of decoupled (non-interacting) systems are also presented. The results are applied in two examples: the one- and three-degree-of-freedom configurations. These demonstrate that the standard configuration is one encompassing all possible feedback configurations. Each chapter is completed by a group of worked examples, which reveal additional insights and extensions of the theory presented in the chapter. Three of the examples illustrate the application of the theory to two physical cases: the depth and pitch control of a submarine and the control of a Rosenbrock process. In the latter case, designs with and without decoupling are compared. This book provides researchers and graduate students working in feedback control with a valuable reference for Wiener-Hopf theory of multivariable design. Basic knowledge of linear systems and matrix theory is required.
Classic text deals primarily with measurement, interpretation of conductance, chemical potential, and diffusion in electrolyte solutions. Detailed theoretical interpretations, plus extensive tables of thermodynamic and transport properties. 1970 edition.
Proceedings of the European Control Conference 1991, July 2-5, 1991, Grenoble, France
This book presents the concepts and algorithms of advanced industrial process control and on-line optimization within the framework of a multilayer structure. It describes the interaction of three separate layers of process control: direct control, set-point control, and economic optimization. The book features illustrations of the methodologies and algorithms by worked examples and by results of simulations based on industrial process models.
A Proceedings Volume from the 2nd IFAC Conference, Bratislava, Slovak Republic, 7-10 September 2003
Active Control of Noise and Vibration
Hybrid Systems: Computation and Control
Advanced Control of Industrial Processes
Advances in Flight Control Systems
Multivariable Control Systems
Instrument Engineers' Handbook, Volume Two

Volume II of a two-part series, this book features 74 problems from various branches of mathematics. Topics include points and lines, topology, convex polygons, theory of primes, and other subjects. Complete solutions.
This book focuses on control techniques for LCL-type grid-connected inverters to improve system stability, control performance and suppression ability of grid current harmonics. Combining a detailed theoretical analysis with design examples and experimental validations, the book offers an essential reference guide for graduate students and researchers in power electronics, as well as engineers engaged in developing grid-connected inverters for renewable energy generation systems.
This book collects together in one volume a number of suggested control engineering solutions which are intended to be representative of solutions applicable to a broad class of control problems. It is neither a control theory book nor a handbook of laboratory experiments, but it does include both the basic theory of control and associated practical laboratory set-ups to illustrate the solutions proposed.
This major work is the first to treat the active control of both sound and vibration in a unified way. It outlines the fundamental concepts, explains how a reliable and stable system can be designed and implemented, and details the pitfalls . It covers sound in ducts, sound radiation, sound transmission into enclosures, structural vibration and isolation, electronic control system design, and sensors and actuators.
Control Engineering Solutions
Second International Workshop, HSCC'99, Berg en Dal, The Netherlands, March 29-31, 1999 Proceedings
Constrained Control and Estimation
Control System Design
Digital Control Engineering
Proceedings of the 3rd International Conference on Intelligent Technologies and Engineering Systems (ICITES2014)
Electrolyte Solutions
Volume I of a two-part series, this book features a broad spectrum of 100 challenging problems related to probability theory and combinatorial analysis. Most can be solved with elementary mathematics. Complete solutions.
Test Prep for Control Systems—GATE, PSUS AND ES Examination
These Proceedings contain a selection of papers presented at the first IFAC Symposium on Design Methods of Control Systems. The volume contains three plenary papers and 97 technical papers, the latter classified under 15 section headings, as listed in the contents.
Trends and Progress in System Identification is a three-part book that focuses on model considerations, identification methods, and experimental conditions involved in system identification. Organized into 10 chapters, this book begins with a discussion of model method in system identification, citing four examples differing on the nature of the models involved, the nature of the fields, and their goals. Subsequent chapters describe the most important aspects of model theory; the ""classical"" methods and time series estimation; application of least squares and related techniques for the estimation of dynamic system parameters; the maximum likelihood and error prediction methods; and the modern development of statistical methods. Non-parametric approaches, identification of nonlinear systems by piecewise approximation, and the minimax identification are then explained. Other chapters explore the Bayesian approach to system identification; choice of input signals; and choice and effect of different feedback configurations in system identification. This book will be useful for control engineers, system scientists, biologists, and members of other disciplines dealing withdynamical relations.
Design of Linear Multivariable Feedback Control Systems
A Transfer Function Approach
Fundamentals, Principles, Methods, Examples
Techniques and Applications
Nonlinear Control Systems Design 1989
Process Control and Optimization
Trends and Progress in System Identification

Introduction to state-space methods covers feedback control; state-space representation of dynamic systems and dynamics of linear systems; frequency-domain analysis; controllability and observability; shaping the dynamic response; more. 1986 edition.
Covers PID control systems from the very basics to the advanced topics This book covers the design, implementation and automatic tuning of PID control systems with operational constraints. It provides students, researchers, and industrial practitioners with everything they need to know about PID control systems—from classical tuning rules and model-based design to constraints, automatic tuning, cascade control, and gain scheduled control. PID Control System Design and Automatic Tuning using MATLAB/Simulink introduces PID control system structures, sensitivity analysis, PID control design, implementation with constraints, disturbance observer-based PID control, gain scheduled PID control systems, cascade PID control systems, PID control design for complex systems, automatic tuning and applications of PID control to unmanned aerial vehicles. It also presents resonant control systems relevant to many engineering applications. The implementation of PID control and resonant control highlights how to deal with operational constraints. Provides unique coverage of PID Control of unmanned aerial vehicles (UAVs), including mathematical models of multi-rotor UAVs, control strategies of UAVs, and automatic tuning of PID controllers for UAVs Provides detailed descriptions of automatic tuning of PID control systems, including relay feedback control systems, frequency response estimation, Monte-Carlo simulation studies, PID controller design using frequency domain information, and MATLAB/Simulink simulation and implementation programs for automatic tuning Includes 15 MATLAB/Simulink tutorials, in a step-by-step manner, to illustrate the design, simulation, implementation and automatic tuning of PID control systems Assists lecturers, teaching assistants, students, and other readers to learn PID control with constraints and apply the control theory to various areas. Accompanying website includes lecture slides and MATLAB/ Simulink programs PID Control System Design and Automatic Tuning using MATLAB/Simulink is intended for undergraduate electrical, chemical, mechanical, and aerospace engineering students, and will greatly benefit postgraduate students, researchers, and industrial personnel who work with control systems and their applications.
This book includes the original, peer reviewed research from the 3rd International Conference on Intelligent Technologies and Engineering Systems (ICITES2014), held in December, 2014 at Cheng Shiu University in Kaohsiung, Taiwan. Topics covered include: Automation and robotics, fiber optics and laser technologies, network and communication systems, micro and nano technologies and solar and power systems. This book also Explores emerging technologies and their application in a broad range of engineering disciplines Examines fiber optics and laser technologies Covers biomedical, electrical, industrial and mechanical systems Discusses multimedia systems and applications, computer vision and image & video signal processing
This book presents recent advances and developments in control, automation, robotics, and measuring techniques. It presents contributions of top experts in the fields, focused on both theory and industrial practice. The particular chapters present a deep analysis of a specific technical problem which is in general followed by a numerical analysis and simulation, and results of an implementation for the solution of a real world problem. The presented theoretical results, practical solutions and guidelines will be useful for both researchers working in the area of engineering sciences and for practitioners solving industrial problems.
Selected Papers from the IFAC Symposium, Capri, Italy, 14-16 June 1989
The Wiener-Hopf Approach using Transforms and Spectral Factorization
Control Techniques for LCL-Type Grid-Connected Inverters
Volume 3

Control System Fundamentals
Challenging Mathematical Problems with Elementary Solutions

Digital controllers are part of nearly all modern personal, industrial, and transportation systems. Every senior or graduate student of electrical, chemical or mechanical engineering should therefore be familiar with the basic theory of digital controllers. This new text covers the fundamental principles and applications of digital control engineering, with emphasis on engineering design. Fadali and Visioli cover analysis and design of digitally controlled systems and describe applications of digital controls in a wide range of fields. With worked examples and Matlab applications in every chapter and many end-of-chapter assignments, this text provides both theory and practice for those coming to digital control engineering for the first time, whether as a student or practicing engineer. Extensive Use of computational tools: Matlab sections at end of each chapter show how to implement concepts from the chapter Frees the student from the drudgery of mundane calculations and allows him to consider more subtle aspects of control system analysis and design An engineering approach to digital controls: emphasis throughout the book is on design of control systems. Mathematics is used to help explain concepts, but throughout the text discussion is tied to design and implementation. For example coverage of analog controls in chapter 5 is not simply a review, but is used to show how analog control systems map to digital control systems Review of Background Material: contains review material to aid understanding of digital control analysis and design. Examples include discussion of discrete-time systems in time domain and frequency domain (reviewed from linear systems course) and root locus design in s-domain and z-domain (reviewed from feedback control course) Inclusion of Advanced Topics In addition to the basic topics required for a one semester senior/graduate class, the text includes some advanced material to make it suitable for an introductory graduate level class or for two quarters at the senior/graduate level. Examples of optional topics are state-space methods, which may receive brief coverage in a one semester course, and nonlinear discrete-time systems Minimal Mathematics Prerequisites The mathematics background required for understanding most of the book is based on what can be reasonably expected from the average electrical, chemical or mechanical engineering senior. This background includes three semesters of calculus, differential equations and basic linear algebra. Some texts on digital control require more
For both undergraduate and graduate courses in Control System Design. Using a "how to do it" approach with a strong emphasis on real-world design, this text provides comprehensive, single-source coverage of the full spectrum of control system design. Each of the text's 8 parts covers an area in control--ranging from signals and systems (Bode Diagrams, Root Locus, etc.), to SISO control (including PID and Fundamental Design Trade-Offs) and MIMO systems (including Constraints, MPC, Decoupling, etc.).
This volume contains the proceedings of the Second International Workshop on Hybrid Systems: Computation and Control (HSCC ' 99) to be held March 29- 31, 1999, in the village Berg en Dal near Nijmegen, The Netherlands. The rst workshop of this series was held in April 1998 at the University of California at Berkeley. The series follows meetings that were initiated by Anil Nerode at Cornell University. The proceedings of those meetings were published in the Springer-Verlag LNCS Series, Volumes 736, 999, 1066, 1201, and 1273. The p- ceedings of the rst workshop of the new series was published in LNCS 1386. The focus of the workshop is on modeling, control, synthesis, design, and ve- cation of hybrid systems. A hybrid system is a theoretical model for a computer controlled engineering system, with a dynamics that evolves both in a discrete state set and in a family of continuous state spaces. Research is motivated by, for example, control of electro-mechanical systems (robots), air tra c control, control of automated freeways, and chemical process control. The emerging - search area of hybrid systems overlaps both with computer science and with control theory. The interaction between researchers from these elds is expected to be fruitfull for the development of the area of hybrid systems.
Recent developments in constrained control and estimation have created a need for this comprehensive introduction to the underlying fundamental principles. These advances have significantly broadened the realm of application of constrained control. - Using the principal tools of prediction and optimisation, examples of how to deal with constraints are given, placing emphasis on model predictive control. - New results combine a number of methods in a unique way, enabling you to build on your background in estimation theory, linear control, stability theory and state-space methods. - Companion web site, continually updated by the authors. Easy to read and at the same time containing a high level of technical detail, this self-contained, new approach to methods for constrained control in design will give you a full understanding of the subject.
Adaptive Systems in Control and Signal Processing 1986
The Control Handbook
Theory and Design, Third Edition
Course Keeping and Roll Stabilisation Using Rudder and Fins
Its Effects and Their Prevention
Control Systems Design 2003 (CSD '03)
Computer-Controlled Systems
This book focuses on control design with continual references to the practical aspects of implementation. While the concepts of multivariable control are justified, the book emphasizes the need to maintain student interest and motivation over exhaustively rigorous mathematical proof.
Sifting through the variety of control systems applications can be a chore. Diverse and numerous technologies inspire applications ranging from float valves to microprocessors. Relevant to any system you might use, the highly adaptable Control System Fundamentals fills your need for a comprehensive treatment of the basic principles of control system engineering. This overview furnishes the underpinnings of modern control systems. Beginning with a review of the required mathematics, major subsections cover digital control and modeling. An international panel of experts discusses the specification of control systems, techniques for dealing with the most common and important control system nonlinearities, and digital implementation of control systems, with complete references. This framework yields a primary resource that is also capable of directing you to more detailed articles and books. This self-contained reference explores the universal aspects of control that you need for any application. Reliable, up-to-date, and versatile, Control System Fundamentals answers your basic control systems questions and acts as an ideal starting point for approaching any control problem.
This second IFAC workshop discusses the variety and applications of adaptive systems in control and signal processing. The various approaches to adaptive control systems are covered and their stability and adaptability analyzed. The volume also includes papers taken from two poster sessions to give a concise and comprehensive overview/treatment of this increasingly important field.
This volume features computational tools that can be applied directly and are explained with simple calculations, plus an emphasis on control system principles and ideas. Includes worked examples, MATLAB macros, and solutions manual.
System Design Automation
PID and Predictive Control of Electrical Drives and Power Converters using MATLAB / Simulink
Model Predictive Control System Design and Implementation Using MATLAB®
Windup in Control
Second Revised Edition
Proceedings of the 2nd IFAC Workshop, Lund, Sweden, 1-3 July 1986
An Optimisation Approach

Model Predictive Control System Design and Implementation Using MATLAB® proposes methods for design and implementation of MPC systems using basis functions that confer the following advantages: - continuous- and discrete-time MPC problems solved in similar design frameworks; - a parsimonious parametric representation of the control trajectory gives rise to computationally efficient algorithms and better on-line performance; and - a more general discrete-time representation of MPC design that becomes identical to the traditional approach for an appropriate choice of parameters. After the theoretical presentation, coverage is given to three industrial applications. The subject of quadratic programming, often associated with the core optimization algorithms of MPC is also introduced and explained. The technical contents of this book is mainly based on advances in MPC using state-space models and basis functions. This volume includes numerous analytical examples and problems and MATLAB® programs and exercises.
engineers into a single volume whilst concentrating on two important research control design problems: autopilots with rudder-roll stabilization and fin and combined rudder-fin stabilization. He has been guided by some of the leading marine control academics, in particular Mogens Blanke and Thor Fossen; indeed Chapters 3 and 4 on kinematics and kinetics of ship motion are jointly authored with Professor Fossen. There are some 240 cited references an invaluable resource for interested readers. The volume is likely to appeal to a wide range of readers who will each be able to extract something different from the various parts of the monograph. Part I has some four chapters on the modelling fundamentals including kinematics, dynamics and actuators. Part II is a very useful survey of the ship roll stabilization problem and how ship roll performance is measured and assessed. This clearly motivates the human necessity for roll-reduction and roll stabilization. Parts III and IV move on to the control systems aspects of the various stabilization designs. Valuable material here includes a study of system performance limitations as caused by the presence of non-minimum phase characteristics and actuator saturation. Chapter 10 has an interesting historical review of these marine control problems stretching back some thirty-years into the 1970s.
In the last two decades, the development of specific methodologies for the control of systems described by nonlinear mathematical models has attracted an ever increasing interest. New breakthroughs have occurred which have aided the design of nonlinear control systems. However there are still limitations which must be understood, some of which were addressed at the IFAC Symposium in Capri. The emphasis was on the methodological developments, although a number of the papers were concerned with the presentation of applications of nonlinear design philosophies to actual control problems in chemical, electrical and mechanical engineering.
impossible to access. It has been widely scattered in papers, reports, and proceedings ofsymposia, with different authors employing different symbols and terms. But now thereis a book that covers all aspects of this dynamic topic in a systematic manner.Featuring consistent terminology and compatible notation, and emphasizing unifiedstrategies, Adaptive Control Systems provides a comprehensive, integrated accountof basic concepts, analytical tools, algorithms, and a wide variety of application trendsand techniques.Adaptive Control Systems deals not only with the two principal approachesmodelreference adaptive control and self-tuning regulators-but also considers otheradaptive strategies involving variable structure systems, reduced order schemes, predictivecontrol, fuzzy logic, and more. In addition, it highlights a large number of practical applicationsin a range of fields from electrical to biomedical and aerospace engineering ...and includes coverage of industrial robots.The book identifies current trends in the development of adaptive control systems ...delineates areas for further research . : . and provides an invaluable bibliography of over1,200 references to the literature.The first authoritative reference in this important area of work, Adaptive ControlSystems is an essential information source for electrical and electronics, R&D,chemical, mechanical, aerospace, biomedical, metallurgical, marine, transportation, andpower plant engineers. It is also useful as a text in professional society seminars and inhousetraining programs for personnel involved with the control of complex systems, andfor graduate students engaged in the study of adaptive control systems.
New Trends in Design of Control Systems 1994
Selected Papers from the IFAC Symposium, Zurich, Switzerland, 4 - 6 September 1991
Adaptive Control Systems
A Practical Approach
Ifac Series for Graduates, Research Workers & Practising Engineers
European Control Conference 1991
An Engineering Approach
The latest update to Bela Liptak's acclaimed "bible" of instrument engineering is now available. Retaining the format that made the previous editions bestsellers in their own right, the fourth edition of Process Control and Optimization continues the tradition of providing quick and easy access to highly practical information. The authors are practicing engineers, not theoretical people from academia, and their from-the-trenches advice has been repeatedly tested in real-life applications. Expanded coverage includes descriptions of overseas manufacturer's products and concepts, model-based optimization in control theory, new major inventions and innovations in control valves, and a full chapter devoted to safety. With more than 2000 graphs, figures, and tables, this all-inclusive encyclopedic volume replaces an entire library with one authoritative reference. The fourth edition brings the content of the previous editions completely up to date, incorporates the developments of the last decade, and broadens the horizons of the work from an American to a global perspective. Béla G. Lipták speaks on Post-Oil Energy Technology on the AT&T Tech Channel.
Computer-Controlled Systems with Delay is a systematic study of the problems of analysis and synthesis for multidimensional sampled-data (SD) systems with delay. It is based on the frequency polynomial method, in which the concept of a parametric transfer matrix (PTM) plays a key role. Until now, no alternative general methods have been available to solve the above problems. The text is divided into three parts: background information from the theory of polynomial and rational matrices, helps the reader to acquire the basic understanding necessary to use the main content of the book without addressing additional sources; methods for the mathematical description of multidimensional SD systems with delay, based on the concept of the PTM; and optimization methods for multidimensional SD systems with delay, including H2 and L2 optimization as well as H2 optimization for colored input signals. The monograph is completed by three appendices. An algorithm for constructing the set of pathological sampling periods for a continuous SISO object with delay is provided first. MATLAB®-toolbox algorithms representing methods described in the book and application examples for selected optimization problems are given in the second. A solution to the problem of guaranteeing the required performance in a class of stochastic disturbances for SD systems with delay is considered in the third. Computer-Controlled Systems with Delay is intended for engineers, scientists and teachers working in modern control theory. It will also benefit post-graduate students taking courses in related disciplines. The book continues the description of the authors research results on developing methods for SD systems theory which are based on the PTM concept and published in the monographs Computer Controlled Systems and Multivariable Computer-controlled Systems.
Design automation of electronic and hybrid systems is a steadily growing field of interest and a permanent challenge for researchers in Electronics, Computer Engineering and Computer Science. System Design Automation presents some recent results in design automation of different types of electronic and mechatronic systems. It deals with various topics of design automation, ranging from high level digital system synthesis, through analogue and heterogeneous system analysis and design, up to system modeling and simulation. Design automation is treated from the aspects of its theoretical fundamentals, its basic approach and its methods and tools. Several application cases are presented in detail. The book consists of three chapters: High-Level System Synthesis (Digital Hardware/Software Systems). Here embedded systems, distributed systems and processor arrays as well as hardware-software codesign are treated. Also three special application cases are discussed in detail; Analog and Heterogeneous System Design (System Approach and Methodology). This chapter copes with the analysis and design of hybrid systems comprised of analog and digital, electronic and mechanical components; System Simulation and Evaluation (Methods and Tools). In this chapter object-oriented Modelling, analog system simulation including fault-simulation, parameter optimization and system validation are regarded. The contents of the book are based on material presented at the Workshop System Design Automation (SDA 2000) organised by the Sonderforschungsbereich 358 of the Deutsche Forschungsgemeinschaft at TU Dresden.
A timely introduction to current research on PID andpredictive control by one of the leading authors on thesubject PID and Predictive Control of Electric Drives and PowerSupplies using MATLAB/Simulink examines the classical controlsystem strategies, such as PID control, feed-forward control andcascade control, which are widely used in current practice. The authors share their experiences in actual design andimplementation of the control systems on laboratory test-beds,taking the reader from the fundamentals through to moresophisticated design and analysis. The bookcontains sections on closed-loop performance analysis in bothfrequency domain and time domain, presented to help the designer inselection of controller parameters and validation of the controlsystem. Continuous-time model predictive control systems aredesigned for the drives and power supplies, and operationalconstraints are imposed in the design. Discrete-time model predictive control systems are designed basedon the discretization of the physical models, which will appeal toreaders who are more familiar with sampled-data control system.Soft sensors and observers will be discussed for low costimplementation. Resonant control of the electric drives andpower supply will be discussed to deal with the problems of bias insensors and unbalanced three phase AC currents. Brings together both classical control systems and predictivecontrol systems in a logical style from introductory through toadvanced levels Demonstrates how simulation and experimental results are usedto support theoretical analysis and the proposed designalgorithms MATLAB and Simulink tutorials are given in each chapter to showthe readers how to take the theory to applications. Includes MATLAB and Simulink software using xPC Target forteaching purposes A companion website is available Researchers and industrial engineers; and graduate students onelectrical engineering courses will find this a valuableresource.
Computer-Controlled Systems with Delay
Ship Motion Control
Control Systems GATE, PSUS AND ES Examination
Design Methods of Control Systems
System Identification, Environmental Modelling, and Control System Design
Implementation in the DiaSter System
Computer control systems are developing rapidly, therefore an insight of the latest trends in the design of control systems will increase the success of future developments. This publication brings together the latest key papers on research and development trends in this field, allowing both academics and industrial practioners to find new insights and gain from each other's experience.
Nonlinear problems in flight control have stimulated cooperation among engineers and scientists from a range of disciplines. Developments in computer technology allowed for numerical solutions of nonlinear control problems, while industrial recognition and applications of nonlinear mathematical models in solving technological problems is increasing. The aim of the book Advances in Flight Control Systems is to bring together reputable researchers from different countries in order to provide a comprehensive coverage of advanced and modern topics in flight control not yet reflected by other books. This product comprises 14 contributions submitted by 38 authors from 11 different countries and areas. It covers most of the currents main streams of flight control researches, ranging from adaptive flight control mechanism, fault tolerant flight control, acceleration based flight control, helicopter flight control, comparison of flight control systems and fundamentals. According to these themes the contributions are grouped in six categories, corresponding to six parts of the book.
Modern control systems are complex in the sense of implementing numerous functions, such as process variable processing, digital control, process monitoring and alarm indication, graphic visualization of process running, or data exchange with other systems or databases. This book conveys a description of the developed DiaSter system as well as characteristics of advanced original methods of modeling, knowledge discovery, simulator construction, process diagnosis, as well as predictive and supervision control applied in the system. The system allows early recognition of abnormal states of industrial processes along with faults or malfunctions of actuators as well as technological and measuring units. The universality of solutions implemented in DiaSter facilitates its broad application, for example, in the power, chemical, pharmaceutical, metallurgical and food industries. The system is a world-scale unique solution, and due to its open architecture it can be connected practically with any other control systems. The monograph presents theoretical and practical results of research into fault diagnosis and control conducted over many years within the cooperation of Polish research teams from the Warsaw University of Technology, the University of Zielona Góra, the Silesian University of Technology in Gliwice, and the Technical University of Rzeszów. The book will be of great interest to researchers and advanced students in automatic control, technical diagnostics and computer engineering, and to engineers tasked with the development of advanced control systems of complex industrial processes.
Control System DesignPearson