

Slotine Nonlinear Control Solution Exercise

This introduction to applied nonlinear dynamics and chaos places emphasis on teaching the techniques and ideas that will enable students to take specific dynamical systems and obtain some quantitative information about their behavior. The new edition has been updated and extended throughout, and contains a detailed glossary of terms. From the reviews: "Will serve as one of the most eminent introductions to the geometric theory of dynamical systems." --Monatshefte für Mathematik

For a first course on nonlinear control that can be taught in one semester This book emerges from the award-winning book, Nonlinear Systems, but has a distinctly different mission and organization. While Nonlinear Systems was intended as a reference and a text on nonlinear system analysis and its application to control, this streamlined book is intended as a text for a first course on nonlinear control. In Nonlinear Control, author Hassan K. Khalil employs a writing style that is intended to make the book accessible to a wider audience without compromising the rigor of the presentation. Teaching and Learning Experience This program will provide a better teaching and learning experience—for you and your students. It will help: Provide an Accessible Approach to Nonlinear Control: This streamlined book is intended as a text for a first course on nonlinear control that can be taught in one semester. Support Learning: Over 250 end-of-chapter exercises give students plenty of opportunities to put theory into action.

COLLEGE ALGEBRA AND CALCULUS: AN APPLIED APPROACH, Second Edition provides your students a comprehensive resource for their college algebra and applied calculus courses. The mathematical concepts and applications are consistently presented in the same tone and pedagogy to promote confidence and a smooth transition from one course to the next. The consolidation of content for two courses in a single text saves you time in your course--and saves your students the cost of an extra textbook. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

This book is written in such a way that the level of mathematical sophistication builds up from chapter to chapter. It has been reorganized into four parts: basic analysis, analysis of feedback systems, advanced analysis, and nonlinear feedback control. Updated content includes subjects which have proven useful in nonlinear control design in recent years-- new in the 3rd edition are: expanded treatment of passivity and passivity-based control; integral control, high-gain feedback, recursive methods, optimal stabilizing control, control Lyapunov functions, and observers. For use as a self-study or reference guide by engineers and applied mathematicians.

Hybrid Feedback Control

Optimal and Robust Control

Applied Mechanics Reviews

Advanced Mathematical Methods with Maple

Analysis and Control of Nonlinear Process Systems

This classic work gives an excellent overview of the subject, with an emphasis on clarity, explanation, and motivation. Extensive exercises and a valuable section containing hints and answers make this an excellent text for both classroom use and independent study.

Mathematical programming: an overview; solving linear programs; sensitivity analysis; duality in linear programming; mathematical programming in practice; integration of strategic and tactical planning in the aluminum industry; planning the mission and composition of the U.S. merchant Marine fleet; network models; integer programming; design of a naval tender job shop; dynamic programming; large-scale systems; nonlinear programming; a system for bank portfolio planning; vectors and matrices; linear programming in matrix form; a labeling algorithm for the maximun-flow network problem.

Emphasises the power of mathematics to provide quantitative insights across the whole area of solid mechanics; accessible and comprehensive.

A user-friendly student guide to computer-assisted algebra with mathematical software packages such as Maple.

Bilinear Control Systems

Differential Equations, Modeling, and Computation

Nonlinear Systems

Nonlinear Stochastic Evolution Problems in Applied Sciences

24th International Conference on Industrial Engineering and Other Applications of Applied Intelligent Systems, IEA/AIE 2011, Syracuse, NY, USA, June 28 - July 1, 2011, Proceedings, Part II

Partial differential equations are used in mathematical models of a huge range of real-world phenomena, from electromagnetism to financial markets. This new edition of Applied PDEs contains many new sections and exercises Including, American options, transform methods, free surface flows, linear elasticity and complex characteristics.

A groundbreaking introduction to vectors, matrices, and least squares for engineering applications, offering a wealth of practical examples.

Classic text/reference suitable for undergraduate and graduate engineering students. Topics include real variable theory, complex variables, linear analysis, partial and ordinary differential equations, and other subjects. Includes answers to selected exercises. 1978 edition.

This straightforward text makes the complicated but powerful methods of non-linear control accessible to process engineers. Not only does it cover the necessary mathematics, but it consistently refers to the widely-known finite-dimensional linear time-invariant continuous case as a basis for extension to the nonlinear situation.

Foundations and Extensions

Nonlinear Control, Global Edition

Numerical Analysis

Mathematical Control Theory

Modern Approaches in Applied Intelligence

Stochastic differential equations are differential equations whose solutions are stochastic processes. They exhibit appealing mathematical properties that are useful in modeling uncertainties and noisy phenomena in many disciplines. This book is motivated by applications of stochastic differential equations in target tracking and medical technology and, in particular, their use in methodologies such as filtering, smoothing, parameter estimation, and machine learning. It builds an intuitive hands-on understanding of what stochastic differential equations are all about, but also covers the essentials of It calculus, the central theorems in the field, and such approximation schemes as stochastic Runge-Kutta. Greater emphasis is given to solution methods than to analysis of theoretical properties of the equations. The book's practical approach assumes only prior understanding of ordinary differential equations. The numerous worked examples and end-of-chapter exercises include application-driven derivations and computational assignments. MATLAB/Octave source code is available for download, promoting hands-on work with the methods. This book constitutes the refereed proceedings of the 19th International Conference on Industrial and Engineering Applications of Artificial Intelligence and Expert Systems, IEA/AIE 2006, held in Annecy, France, June 2006. The book presents 134 revised full papers together with 3 invited contributions, organized in topical sections on multi-agent systems, decision-support, genetic algorithms, data-mining and knowledge discovery, fuzzy logic, knowledge engineering, machine learning, speech recognition, systems for real life applications, and more.

An Invitation to Applied Mathematics: Differential Equations, Modeling, and Computation introduces the reader to the methodology of modern applied mathematics in modeling, analysis, and scientific computing with emphasis on the use of ordinary and partial differential equations. Each topic is introduced with an attractive physical problem, where a mathematical model is constructed using physical and constitutive laws arising from the conservation of mass, conservation of momentum, or Maxwell's electrodynamics. Relevant mathematical analysis (which might employ vector calculus, Fourier series, nonlinear ODEs, bifurcation theory, perturbation theory, potential theory, control theory, or probability theory) or scientific computing (which might include Newton's method, the method of lines, finite differences, finite elements, finite volumes, boundary elements, projection methods, smoothed particle hydrodynamics, or Lagrangian methods) is developed in context and used to make physically significant predictions. The target audience is advanced undergraduates (who have at least a working knowledge of vector calculus and linear ordinary differential equations) or beginning graduate students. Readers will gain a solid and exciting introduction to modeling, mathematical analysis, and computation that provides the key ideas and skills needed to enter the wider world of modern applied mathematics. Presents an integrated wealth of modeling, analysis, and numerical methods in one volume Provides practical and comprehensible introductions to complex subjects, for example, conservation laws, CFD, SPH, BEM, and FEM Includes a rich set of applications, with more appealing problems and projects suggested

Geared primarily to an audience consisting of mathematically advanced undergraduate or beginning graduate students, this text may additionally be used by engineering students interested in a rigorous, proof-oriented systems course that goes beyond the classical frequency-domain material and more applied courses. The minimal mathematical background required is a working knowledge of linear algebra and differential equations. The book covers what constitutes the common core of control theory and is unique in its emphasis on foundational aspects. While covering a wide range of topics written in a standard theorem/proof style, it also develops the necessary techniques from scratch. In this second edition, new chapters and sections have been added, dealing with time optimal control of linear systems, variational and numerical approaches to nonlinear control, nonlinear controllability via Lie-algebraic methods, and controllability of recurrent nets and of linear systems with bounded controls.

Industrial Mathematics and Complex Systems

Matrices in Action

Advances in Applied Artificial Intelligence

Introduction to Applied Linear Algebra

Applied Mathematical Programming

The mathematical theory of control became a ?eld of study half a century ago in attempts to clarify and organize some challenging practical problems and the methods used to solve them. It is known for the breadth of the mathematics it uses and its cross-disciplinary vigor. Its literature, which can be found in Section 93 of Mathematical Reviews, was at one time dominated by the theory of linear control systems, which mathematically are described by linear differential equations forced by additive control inputs. That theory led to well-regarded numerical and symbolic computational packages for control analysis and design. Nonlinear control problems are also important; in these either the underlying dynamical system is nonlinear or the controls are applied in a non-additive way. The last four decades have seen the development of theoretical work on nonlinear control problems based on differential manifold theory, nonlinear analysis, and several other mathematical disciplines. Many of the problems that had been solved in linear control theory, plus others that are new and distinctly nonlinear, have been addressed; some resulting general definitions and theorems are adapted in this book to the bilinear case.

The essential introduction to the principles and applications of feedback systems—now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of Feedback Systems is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory

This new edition features the latest tools for modeling, characterizing, and solving partial differential equations The Third Edition of this classic text offers a comprehensive guide to modeling, characterizing, and solving partial differential equations (PDEs). The author provides all the theory and tools necessary to solve problems via exact, approximate, and numerical methods. The Third Edition retains all the hallmarks of its previous editions, including an emphasis on practical applications, clear writing style and logical organization, and extensive use of real-world examples. Among the new and revised material, the book features:
* A new section at the end of each original chapter, exhibiting the use of specially constructed Maple procedures that solve PDEs via many of the methods presented in the chapters. The results can be evaluated numerically or displayed graphically.
* Two new chapters that present finite difference and finite element methods for the solution of PDEs. Newly constructed Maple procedures are provided and used to carry out each of these methods. All the numerical results can be displayed graphically.
* A related FTP site that includes all the Maple code used in the text.
* New exercises in each chapter, and answers to many of the exercises are provided via the FTP site. A supplementary Instructor's Solutions Manual is available. The book begins with a demonstration of how the three basic types of equations—parabolic, hyperbolic, and elliptic—can be derived from random walk models. It then covers an exceptionally broad range of topics, including questions of stability, analysis of singularities, transform methods, Green's functions, and perturbation and asymptotic treatments. Approximation methods for simplifying complicated problems and solutions are described, and linear and nonlinear problems not easily solved by standard methods are examined in depth. Examples from the fields of engineering and physical sciences are used liberally throughout the text to help illustrate how theory and techniques are applied to actual problems. With its extensive use of examples and exercises, this text is recommended for advanced undergraduates and graduate students in engineering, science, and applied mathematics, as well as professionals in any of these fields. It is possible to use the text, as in the past, without use of the new Maple material.

This volume deals with the analysis of nonlinear evolution problems described by partial differential equations having random or stochastic parameters. The emphasis throughout is on the actual determination of solutions, rather than on proving the existence of solutions, although mathematical proofs are given when this is necessary from an applications point of view. The content is divided into six chapters. Chapter 1 gives a general presentation of mathematical models in continuum mechanics and a description of the way in which problems are formulated. Chapter 2 deals with the problem of the evolution of an unconstrained system having random space-dependent initial conditions, but which is governed by a deterministic evolution equation. Chapter 3 deals with the initial-boundary value problem for equations with random initial and boundary conditions as well as with random parameters where the randomness is modelled by stochastic separable processes. Chapter 4 is devoted to the initial-boundary value problem for models with additional noise, which obey Ito-type partial differential equations. Chapter 5 is essential devoted to the qualitative and quantitative analysis of the chaotic behaviour of systems in continuum physics. Chapter 6 provides indications on the solution of ill-posed and inverse problems of stochastic type and suggests guidelines for future research. The volume concludes with an Appendix which gives a brief presentation of the theory of stochastic processes. Examples, applications and case studies are given throughout the book and range from those involving simple stochasticity to stochastic illposed problems. For applied mathematicians, engineers and physicists whose work involves solving stochastic problems.

Advanced Theory and Applications

College Algebra and Calculus: An Applied Approach

Probabilistic Structural Dynamics

Linear Programming

Applied Linear Algebra and Matrix Analysis

This textbook develops the essential tools of linear algebra, with the goal of imparting technique alongside contextual understanding. Applications go hand-in-hand with theory, each reinforcing and explaining the other. This approach encourages students to develop not only the technical proficiency needed to go on to further study, but an appreciation for when, why, and how the tools of linear algebra can be used across modern applied mathematics. Providing an extensive treatment of essential topics such as Gaussian elimination, inner products and norms, and eigenvalues and singular values, this text can be used for an in-depth first course, or an application-driven second course in linear algebra. In this second edition, applications have been updated and expanded to include numerical methods, dynamical systems, data analysis, and signal processing, while the pedagogical flow of the core material has been improved. Throughout, the text emphasizes the conceptual connections between each application and the underlying linear algebraic techniques, thereby enabling students not only to learn how to apply the mathematical tools in routine contexts, but also to understand what is required to adapt to unusual or emerging problems. No previous knowledge of linear algebra is needed to approach this text, with single-variable calculus as the only formal prerequisite. However, the reader will need to draw upon some mathematical maturity to engage in the increasing abstraction inherent to the subject. Once equipped with the main tools and concepts from this book, students will be prepared for further study in differential equations, numerical analysis, data science and statistics, and a broad range of applications. The first author's text, Introduction to Partial Differential Equations, is an ideal companion volume, forming a natural extension of the linear mathematical methods developed here.

This well-respected text introduces the theory and application of modern numerical approximation techniques to students taking a one- or two-semester course in numerical analysis. Providing an accessible treatment that only requires a calculus prerequisite, the authors explain how, why, and when approximation techniques can be expected to work—and why, in some situations, they fail. A wealth of examples and exercises develop students' intuition, and demonstrate the subject's practical applications to important everyday problems in math, computing, engineering, and physical science disciplines. The first book of its kind when crafted more than 30 years ago to serve a diverse undergraduate audience, Burden, Faires, and Burden's NUMERICAL ANALYSIS remains the definitive introduction to a vital and practical subject. Important Notice: Media content referenced within the product description or the product text may not be available in the ebook version.

In this work, the authors present a global perspective on the methods available for analysis and design of non-linear control systems and detail specific applications. They provide a tutorial exposition of the major non-linear systems analysis techniques followed by a discussion of available non-linear design methods.

Traditionally, engineers look to established safety factors to build sound structures, but the process is inefficient and often yields less than the desired results. This reference presents a different approach, allowing structural engineers to overcome the unpredictability of traditional modeling systems by developing sophisticated equation sets to solve specific structural problems.

Applied Stochastic Differential Equations

Foundations of Applied Mathematics

A First Course in Applied Mathematics

Scientific Computing with Ordinary Differential Equations

Applied Finite Mathematics

Explore real-world applications of selected mathematical theory, concepts, and methods Exploring related methods that can be utilized in various fields of practice from science and engineering to business, A First Course in Applied Mathematics details how applied mathematics involves predictions, interpretations, analysis, and mathematical

modeling to solve real-world problems. Written at a level that is accessible to readers from a wide range of scientific and engineering fields, the book masterfully blends standard topics with modern areas of application and provides the needed foundation for transitioning to more advanced subjects. The author utilizes MATLAB® to showcase the presented theory and illustrate interesting real-world applications to Google's web page ranking algorithm, image compression, cryptography, chaos, and waste management systems. Additional topics covered include: Linear algebra Ranking web pages Matrix factorizations Least squares Image compression Ordinary differential equations Dynamical systems Mathematical models Throughout the book, theoretical and applications-oriented problems and exercises allow readers to test their comprehension of the presented material. An accompanying website features related MATLAB® code and additional resources. A First Course in Applied Mathematics is an ideal book for mathematics, computer science, and engineering courses at the upper-undergraduate level. The book also serves as a valuable reference for practitioners working with mathematical modeling, computational methods, and the applications of mathematics in their everyday work.

Ocean structures, including ships, boats, piers, docks, rigs and platforms, are subject to fair weather wind and waves, as well as violent storms. A scientific analysis of these structures, under varying conditions, requires a mix of civil engineering, physics and applied mathematics. Chapters by experts in these fields are presented which explore the nonlinear responses of ocean structures to stochastic forcing. Theoretical methods calculate aspects of time, frequency and phase space responses. Probabilities governed by stochastic differential equations arc investigated directly or through moment correlations, such as power spectra. Calculations can also involve level crossing statistics and first passage times. Tiffs book will help scientists study stochastic nonlinear equations and help engineers design for short term survivability of structures in storms and long life in the face of everyday fatigue.

A comprehensive introduction to hybrid control systems and design Hybrid control systems exhibit both discrete changes, or jumps, and continuous changes, or flow. An example of a hybrid control system is the automatic control of the temperature in a room: the temperature changes continuously, but the control algorithm toggles the heater on or off intermittently, triggering a discrete jump within the algorithm. Hybrid control systems feature widely across disciplines, including biology, computer science, and engineering, and examples range from the control of cellular responses to self-driving cars. Although classical control theory provides powerful tools for analyzing systems that exhibit either flow or jumps, it is ill-equipped to handle hybrid control systems. In Hybrid Feedback Control, Ricardo Sanfelice presents a self-contained introduction to hybrid control systems and develops new tools for their analysis and design. Hybrid behavior can occur in one or more subsystems of a feedback system, and Sanfelice offers a unified control theory framework, filling an important gap in the control theory literature. In addition to the theoretical framework, he includes a plethora of examples and exercises, a Matlab toolbox (as well as two open-source versions), and an insightful overview at the beginning of each chapter. Relevant to dynamical systems theory, applied mathematics, and computer science, Hybrid Feedback Control will be useful to students and researchers working on hybrid systems, cyber-physical systems, control, and automation.

This workbook and solutions manual is intended for advanced undergraduate or beginning graduate students as a supplement to a traditional course in numerical mathematics and as preparation for independent research involving numerical mathematics. The solutions manual provides complete MATLAB code and numerical results for each of the exercises in the workbook and will be especially useful for those students without previous MATLAB programming experience. It is also valuable for classroom instructors to help pinpoint the author's intent in each exercise and to provide a model for graders. Upon completion of this material, students will have a working knowledge of MATLAB programming, they will have themselves programmed algorithms encountered in classwork and textbooks, and they will know how to check and verify their own programs against hand calculations and by reference to theoretical results, special polynomial solutions and other specialized solutions. No previous programming experience with MATLAB is necessary.

Applied Mathematical Methods:

Applied Nonlinear Control

Feedback Systems

Stochastically Excited Nonlinear Ocean Structures

Methods for Applied Macroeconomic Research

The two volume set LNAI 6703 and LNAI 6704 constitutes the thoroughly refereed conference proceedings of the 24th International Conference on Industrial Engineering and Other Applications of Applied Intelligent Systems, IEA/AIE 2011, held in Syracuse, NY, USA, in June/July 2011. The total of 92 papers selected for the proceedings were carefully reviewed and selected from 206 submissions. The papers cover a wide number of topics including feature extraction, discretization, clustering, classification, diagnosis, data refinement, neural networks, genetic algorithms, learning classifier systems, Bayesian and probabilistic methods, image processing, robotics, navigation, optimization, scheduling, routing, game theory and agents, cognition, emotion, and beliefs.

The last twenty years have witnessed tremendous advances in the mathematical, statistical, and computational tools available to applied macroeconomists. This rapidly evolving field has redefined how researchers test models and validate theories. Yet until now there has been no textbook that unites the latest methods and bridges the divide between theoretical and applied work. Fabio Canova brings together dynamic equilibrium theory, data analysis, and advanced econometric and computational methods to provide the first comprehensive set of techniques for use by academic economists as well as professional macroeconomists in banking and finance, industry, and government. This graduate-level textbook is for readers knowledgeable in modern macroeconomic theory, econometrics, and computational programming using RATS, MATLAB, or Gauss. Inevitably a modern treatment of such a complex topic requires a quantitative perspective, a solid dynamic theory background, and the development of empirical and numerical methods--which is where Canova's book differs from typical graduate textbooks in macroeconomics and econometrics. Rather than list a series of estimators and their properties, Canova starts from a class of DSGE models, finds an approximate linear representation for the decision rules, and describes methods needed to estimate their parameters, examining their fit to the data. The book is complete with numerous examples and exercises. Today's economic analysts need a strong foundation in both theory and application. Methods for Applied Macroeconomic Research offers the essential tools for the next generation of macroeconomists.

Applied Mathematical Methods covers the material vital for research in today's world and can be covered in a regular semester course. It is the consolidation of the efforts of teaching the compulsory first semester post-graduate applied mathematics course at the Department of Mechanical Engineering at IIT Kanpur in two successive years.

While there are many books on advanced control for specialists, there are few that present these topics for nonspecialists. Assuming only a basic knowledge of automatic control and signals and systems, Optimal and Robust Control: Advanced Topics with MATLAB® offers a straightforward, self-contained handbook of advanced topics and tools in automatic control. Techniques for Controlling System Performance in the Presence of Uncertainty The book deals with advanced automatic control techniques, paying particular attention to robustness—the ability to guarantee stability in the presence of uncertainty. It explains advanced techniques for handling uncertainty and optimizing the control loop. It also details analytical strategies for obtaining reduced order models. The authors then propose using the Linear Matrix Inequalities (LMI) technique as a unifying tool to solve many types of advanced control problems. Topics covered include: LQR and H-infinity approaches Kalman and singular value decomposition Open-loop balancing and reduced order models Closed-loop balancing Passive systems and bounded-real systems Criteria for stability control This easy-to-read text presents the essential theoretical background and provides numerous examples and MATLAB exercises to help the reader efficiently acquire new skills. Written for electrical, electronic, computer science, space, and automation engineers interested in automatic control, this book can also be used for self-study or for a one-semester course in robust control.

Emerging Mathematical Models, Methods and Algorithms

Introduction to Applied Nonlinear Dynamical Systems and Chaos

An Invitation to Applied Mathematics

Applied Linear Algebra

Vectors, Matrices, and Least Squares

The book discusses essential topics in industrial and applied mathematics such as image processing with a special focus on medical imaging, biometrics and tomography. Applications of mathematical concepts to areas like national security, homeland security and law enforcement, enterprise and e-government services, personal information and business transactions, and brain-like computers are also highlighted. These contributions – all prepared by respected academicians, scientists and researchers from across the globe – are based on papers presented at the international conference organized on the occasion of the Silver Jubilee of the Indian Society of Industrial and Applied Mathematics (ISIAM) held from 29 to 31 January 2016 at Sharda University, Greater Noida, India. The book will help young scientists and engineers grasp systematic developments in those areas of mathematics that are essential to properly understand challenging contemporary problems.

Over the last few decades, optimization techniques have been streamlined by the use of computers and artificial intelligence methods to analyze more variables (especially under non-linear, multivariable conditions) more quickly than ever before. This book covers all classical linear and nonlinear optimization techniques while focusing on the standard mathematical engine, MATLAB. As with the first edition, the author uses MATLAB in examples for running computer-based optimization problems. New coverage in this edition includes design optimization techniques such as Multidisciplinary Optimization, Explicit Solution for Boundary Value Problems, and Particle Swarm Optimization.

This new book offers a fresh approach to matrix and linear algebra by providing a balanced blend of applications, theory, and computation, while highlighting their interdependence. Intended for a one-semester course, Applied Linear Algebra and Matrix Analysis places special emphasis on linear algebra as an experimental science, with numerous examples, computer exercises, and projects. While the flavor is heavily computational and experimental, the text is independent of specific hardware or software platforms. Throughout the book, significant motivating examples are woven into the text, and each section ends with a set of exercises.

This book provides an introduction to optimization. It details constrained optimization, beginning with a substantial treatment of linear programming and proceeding to convex analysis, network flows, integer programming, quadratic programming, and convex optimization. Coverage underscores the purpose of optimization: to solve practical problems on a computer. C programs that implement the major algorithms and JAVA tools are available online.

Practical Numerical Mathematics With Matlab: A Workbook And Solutions

Deterministic Finite Dimensional Systems

Mathematics Applied to Continuum Mechanics

Applied Partial Differential Equations

Applied Solid Mechanics

This book addresses the construction, analysis, and interpretation of mathematical models that shed light on significant problems in the physical sciences, with exercises that reinforce, test and extend the reader's understanding. It may be used as an upper level undergraduate or graduate textbook as well as a reference for researchers.

Well-known authors; Includes topics and results that have previously not been covered in a book; Uses many interesting examples from science and engineering; Contains numerous homework exercises; Scientific computing is a hot and topical area

Advanced Topics with MATLAB®

Mathematics Applied to Deterministic Problems in the Natural Sciences

Partial Differential Equations of Applied Mathematics

Applied Optimization with MATLAB Programming

19th International Conference on Industrial, Engineering and Other Applications of Applied Intelligent Systems, IEA/AIE 2006, Annecy, France, June 27-30, 2006, Proceedings