

Speed Control Of Dc Motors With The L292 Switchmode Driver

In the current century, DC motors plays a vital role in industrial areas. The efficient motor, are motor that be able to control the speed. Motor speed is controller by signal representing from microcontroller. In this project, the power converter for DC motor application is developed. One type of common method is by using Pulse Width Modulation (PWM), to control converted AC to DC supply and buck/boost converter are used to step up/step down a voltage or current while DC motor used as a load. Supplies to the DC motor are developed and the output is controlled by using PWM. PIC microcontroller is used to generate the PWM wave which can be varied in duty ratio, in order to create another level of DC voltage. This project converter using Orcad software and also Proteus 7.6 professional. In addition, hardware prototype has been developed based on the circuit designed. The system performance are evaluated and analyzed in comparison with a simulation results, at the end of this project the motor speed will satisfied the desired speed.

This Book Is Prepared For Undergraduate Students Of Various Indian Universities And Those Preparing For Associate Membership Examination Of The Institution Of Electrical Engineers (India) As Well The Diploma In Electrical Engineering Examination Of Various Boards Of Technical Education Covering The Subjects Electric Drives And Control And Utilisation Of Electric Energy. Illumination Deals Extensively With The Principles Of The Interior, Factory Lighting And Flood Lighting Schemes As Well As The Features Of Street Lighting. A Section On Photometric Measurement Is Added Along With A Study Of Halogen Lamps And Energy Saving Fluorescent Lamps. The Chapter On Electric Drives And Control Covers The Recent Trends In Electric Traction Technology. Objective Type Questions Were Incorporated For Self Assessment.

Direct current (DC) motors have variable characteristics and are used extensively in variable-speed drives. DC motor can provide a high starting torque and it is also possible to obtain speed control over wide range. Why do we need a seed motor controller? For example, if we have a DC motor in a robot, if we just apply a constant power to each motor on a robot, maintain a steady speed. It will go slower over carpet, faster over smooth flooring, slower up hill, faster down hill, etc. So, it is important to make a controller to control the speed of DC motor in desired speed. DC motor plays a significant role in modern industrial. These are several types of applications where the load on the DC motor varies over a speed range. The accuracy and good dynamic responses. In home applications, washers, dryers and compressors are good example. In automotive, fuel pump control, electronic steering control, engine control and electric vehicle control are good examples of these. In aerospace, there are a number of applications, like centrifuges, pumps, robotic arm controls, gyroscope controls and

Development of Control Scheme for DC Motor Speed Control Applications

Speed Control of Small D.C. Motors

Utilisation of Electric Power

Adaptive Speed Control of DC Motors Without Rational Transducers

Fundamentals, Types and Applications

Mixed-Signal Embedded Microcontrollers are commonly used in integrating analog components needed to control non-digital electronic systems. They are used in automatically controlled devices and products, such as automobile engine control systems, wireless remote controllers, office machines, home appliances, power tools, and toys. Microcontrollers make it economical to digitally control even more devices and processes by reducing the size and cost, compared to a design that uses a separate microprocessor, memory, and input/output devices. In many undergraduate and post-graduate courses, teaching of mixed-signal microcontrollers and their use for project work has become compulsory. Students face a lot of difficulties when they have to interface a microcontroller with the electronics they deal with. This book addresses some issues of interfacing the microcontrollers and describes some project implementations with the Silicon Lab C8051F020 mixed – signal microcontroller. The intended readers are college and university students specializing in electronics, computer systems engineering, electrical and electronics engineering; researchers involved with electronics based system, practitioners, technicians and in general anybody interested in microcontrollers based projects.

The development of technologies affects the demands of industries at the present time. Thus, automatic control has played a vital role in the advance of engineering and science. In today's industries, control of DC motors is a common practice. Therefore, implementation of DC motor controller is required. There are many types of controller that can be used to implement the elegant and effective output. One of them is by using a PI controller. PI stands for Proportional and Integral Controllers which are designed to eliminate the need for continuous operator attention thus provide automatic control to the system. Cruise control in a car and a house thermostat are common examples of how controllers are used to automatically adjust some variable to hold the measurement (or process variable) at the set-point. This project is focusing on implementing PI controller to control speed of a dc motor. The overall project is divided into two parts. The first part is concern on the simulation using MATLAB simulink where the dc motor is modeled and PI controller is tuned using Ziegler-Nichols rules and software tuning. The second part is implementing the simulation. This part is divided into another two parts, Graphical User Interface (GUI) development and hardware interfacing. GUI is built using National Instrument LabVIEW software with implementation of PI controller. An oscilloscope also had been build there. Hardware interfacing part is built with Mitsumi dc mini-motors. M31E-1 Series, speed sensor and analog to digital converter, DAC8032. As the result, PI controller is capable to control the speed of dc motor followed the result from simulation.

Fuzzy c-means (FCM) Clustering has been used to partition the input-output data and to determine the number of rules. By assuming Gaussian membership function for the premise parts, hybrid learning algorithm is used to update its parameters. This book presents a research work towards the development of a T-S fuzzy model for the speed control of dc motors. To be specific, an attempt is made to design a clustering based fuzzy logic controller for speed control of dc motors. The proposed approach provides a mechanism to obtain the reduced rule-set covering the whole input/output space as well as the parameters of membership functions for each input variable. The entire system has been modeled using MATLAB 7.0/Simulink toolbox.

Speed Control of Dc Motor Using Pwm Technique

How To Control A Dc Motor With An Arduino

Speed Control of DC Motors

ELECTRO-MECHANICAL MODELING OF SEDM(SEPARATELY EXCITED DC MOTOR) & PERFORMANCE IMPROVEMENT USING DIFFERENT INDUSTRIAL CONTROLLERS

Minicomputer Speed Control of DC Motors

Recent advances in LSI technology and the consequent availability of inexpensive but powerful microprocessors have already affected the process control industry in a significant manner. Microprocessors are being increasingly utilized for improving the performance of control systems and making them more sophisticated as well as reliable. Many concepts of adaptive and learning control theory which were considered impractical only 20 years ago are now being implemented. With these developments there has been a steady growth in hardware and software tools to support the microprocessor in its complex tasks. With the current trend of using several microprocessors for performing the complex tasks in a modern control system, a great deal of emphasis is being given to the topic of the transfer and sharing of information between them. Thus the subject of local area networking in the industrial environment has become assumed great importance. The object of this book is to present both hardware and software concepts that are important in the development of microprocessor-based control systems. An attempt has been made to obtain a balance between theory and practice, with emphasis on practical applications. It should be useful for both practicing engineers and students who are interested in learning the practical details of the implementation of microprocessor-based control systems. As some of the related material has been published in the earlier volumes of this series, duplication has been avoided as far as possible.

Academic Paper from the year 2020 in the subject Computer Science - Miscellaneous, , language: English, abstract: In this paper we describe a technical system for DC motor speed control. The speed of DC motor is controlled using Neural Network Based Model Reference and Predictive controllers with the use of Matlab/Simulink. The analysis of the DC motor is done with and without input side Torque disturbance input and the simulation results obtained by comparing the desired and actual speed of the DC motor using random reference and sinusoidal speed inputs for the DC motor with Model Reference and Predictive controllers. The DC motor with Model Reference controller shows almost the actual speed is the same as the desired speed with a good performance than the DC motor with Predictive controller for the system with and without input side disturbance. Finally the comparative simulation result prove the effectiveness of the DC motor with Model Reference controller.

This clear and concise advanced textbook is a comprehensive introduction to power electronics.

Designing Integrated Projects

Speed Control of Sensorless Brushless DC Motor

Projects For You: Motor Speed Arduino

LabVIEW for Electric Circuits, Machines, Drives, and Laboratories

An Engineering Handbook

Electric Motor Control: DC, AC, and BLDC Motors introduces practical drive techniques of electric motors to enable stable and efficient control of many application systems, also covering basic principles of high-performance motor control techniques, driving methods, control theories and power converters. Electric motor drive systems play a critical role in home appliances, motor vehicles, robotics, aerospace and transportation, heating ventilating and cooling equipment's, robotics, industrial machinery and other commercial applications. The book provides engineers with drive techniques that will help them develop motor drive system for their applications. Includes practical solutions and control techniques for industrial motor drive applications currently in use. Contains MATLAB/Simulink simulation files. Enables engineers to understand the applications and advantages of electric motor drive systems.

In this book, Mathematical Modelling of a reference SEDM has been done & Transfer Function has been derived with simulated result. Later Parameter Identification has been carried out to find the suitable design criteria for testing different controllers (P, PI, PD, PID controllers) with the machine. As it turned out to be a stable system (as per Routh-Hurwitz Stability Criterion), different controllers has been used to evaluate the Step response of Open loop & Closed loop system with simulated result. Controller tuning has been done to find the best result for controlling speed of SEDM. Settling time, % Overshoot, Steady-State error & Rise time has been calculated for all the controllers. Later active RC realization of the best fitted controller has been done using Ideal PID Control Algorithm.

Catalog of motors. Answers technical questions on DC motors, speed controls, servo systems, & optical encoders.

Generation and Utilization of Electrical Energy

Brushless DC Motor Controller, AC Gear Motor, Permanent Magnet DC Motor, Large DC Motors, Brushless Electric Motor, Brushless DC Motor, DC Motors, Servo Motor

Novel Algorithms and Techniques in Telecommunications, Automation and Industrial Electronics

Applied Control Theory

Electric Motors and Drives

Generation and Utilization of Electrical Energy is a comprehensive text designed for undergraduate courses in electrical engineering. The text introduces the reader to the generation of electrical energy and then goes on to explain how this energy can be effectively utilized for various applications like welding,

electric traction, illumination, and electrolysis. The detailed explanations of practical applications make this an ideal reference book both inside and outside the classroom.

This book is all about running a brushless DC motor using a sensorless technique. The target of the work was to make a very simple operating method for a brushless motor and formulate a speed control mechanism. Initially the work was started with both considering back-EMF and without considering back-EMF. Because of more complexity in the back-EMF sensing method, and as our intention was to make a simpler and cost effective operation, so finally we assembled our project the without back-EMF sensing. The performance was quite good. However adding back-EMF sensing in this machine can give it more dependability. 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